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zanatska prerada mesa obrada creva pdf.rar. made with the same set of weights $\{\beta_t\}_{t=1}^T$ for all stages; e.g., this approximation is valid when β_t is independent of the fact that it is a stage. : : \ We use $N=2^{28}$ for all experiments, except for the time series experiment in Section \[sec:experiment-4\], where we use $N=2^{10}$. We run the experiments for $T=20$ time-steps in a Monte Carlo (MC) setting to learn from multiple observed samples. We report performance in terms of the average reward across all time-steps, $\hat{\rho}_{\text{ave}} = \frac{1}{T} \sum_{t=1}^T \rho_t$, and the resulting expected return, $\hat{G}_{\text{ave}} = \frac{1}{T} \sum_{t=1}^T G_t$, averaged over the MC samples. For the noise-free experiments (Section [sec:experiments]), we use the ζ_t from the original RL algorithm. In the asynchronous setting (Section [sec:experiments]), we use a separate $\zeta_t^{(\text{asyn})}$ for each time-step; this is to ensure that the random sample is not a corrupted version of the real ζ_t, which would reduce our performance. We compare the following algorithms: [r]{}[0.55]{} 2-stage SCR:\ $\hat{\rho}_{\text{ave}}^{(2)} = \dfrac{1}{T} \sum_{t=1}^T \rho^{(2)}_t$;\ $\hat{G}_{\text{ave}}^{(2)} = \dfrac{1}{T} \sum_{t=1}^T G^{(2)}_t$;\ [$^{\text{(i)}}$]{} [$^{\text{(ii)}}$]{} [$^{\text{(iii)}}$] f988f36e3a

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